

IN THE CLAIMS:

The status of each claim that has been introduced in the above-referenced application is identified in the ensuing listing of the claims. This listing of the claims replaces all previously submitted claims listings.

1. (Currently amended) A hand-held pick-and-place apparatus, comprising:
a grasping element comprising a non-flowing semisolid material including an end for adhesion to a piece to be picked while leaving substantially no residue on the piece;
an elongate body configured to be grasped by a hand of an individual;
a tip secured to an end of the body, the tip including at least one channel through at least a portion of a length thereof, the at least one channel being configured to receive at least a portion of the grasping element, the tip being rotatable relative to the body to define a position of the end for adhesion of the grasping element relative to a free end of the tip, including a picking position in which the end for adhesion protrudes from the free end of the tip to enable adhesion of the piece to the end for adhesion.
2. (Previously presented) The hand-held pick-and-place apparatus of claim 1, wherein the body includes a chamber for receiving at least a portion of the grasping element.
3. (Canceled)
4. (Previously presented) The hand-held pick-and-place apparatus of claim 1, wherein the tip is configured to move longitudinally to a plurality of positions relative to the body to facilitate at least one of exposure and storage of the grasping element.
5. (Previously presented) The hand-held pick-and-place apparatus of claim 4, wherein a tip-engagement element of the body and a body-engagement element of the tip include complementary threading.

6. (Previously presented) The hand-held pick-and-place apparatus of claim 5, further comprising:
a cap configured to receive at least the end for adhesion of the grasping element and to be secured to the tip.

7. (Previously presented) The hand-held pick-and-place apparatus of claim 6, wherein the cap is configured to be secured to the tip such that rotation of the cap results in rotation of the tip.

8. (Previously presented) The hand-held pick and place apparatus of claim 4, further comprising a plunger positioned coaxially within the body and configured to be positioned in-line with the at least one channel of the tip for insertion therein.

9. (Previously presented) The hand-held pick-and-place apparatus of claim 4, further comprising:
an interior fixed element within the body which limits a distance body-engagement element of the tip may be inserted into a chamber of the body.

10. (Previously presented) The hand-held pick-and-place apparatus of claim 1, further comprising:
a cap configured to receive at least the end for adhesion of the grasping element and to be secured in place relative to the body.

11-17 (Canceled)

18. (Currently amended) An adhesive tip for a hand-held pick-and-place apparatus, comprising:

a grasping element comprising non-flowing semisolid material; and

a tip including:

at least one channel extending longitudinally through at least a portion of the tip for receiving at least a portion of the grasping element; and

a body-engagement element configured to be secured to a body of the hand-held pick-and-place apparatus and to be rotated relative to the body so as to cause the grasping element to be extruded from the tip or retracted therein.

19. (Previously presented) The adhesive tip of claim 18, wherein at least one end of the grasping element protrudes from the body-engagement element.

20-40 (Canceled)